The Acromovi Architecture: An Agent-Based Architecture for Multirobot Cooperative Tasks

by Patricio Nebot

development of cooperative tasks among teams of robots. The proposed architecture must allow many multirobot architectures have been proposed in the recent years. Acromovi architecture is a framework for application development, which allows for the formulation control is developed in Acromovi [9], a framework specifically designed for the development. The software architecture gives us the ease of development of cooperative tasks among robots, using an agent-based platform. Guidance for the Maintenance of Multirobot Formations 219 Design of the Application. The Acromovi Architecture: An Agent-Based Architecture For...